Darren Biskup

EDUCATION

University of Illinois, Urbana-Champaign

B.S. Mechanical Engineering, Computer Science Minor

High Honors, James Scholar Honors Program, Dean's List, ASME

RELEVANT COURSEWORK

Computer Control of Mechanical Systems, Engineering Materials, Heat Transfer, Signal Processing, Statics, Dynamics, Solid Mechanics, Fluid Dynamics, Dynamics of Mechanical Systems, Thermodynamics, Algorithms and Data Structures

SKILLS

Computer Aided Design: CATIA 3DEXPERIENCE, Autodesk Fusion360, SolidWorks Computer Programming: C++, Python (OpenCV, scikit-image), and Java. HTML and CSS Technical: Design for Injection Molding, Battery Pack Design, DFM, GD&T, Mechanical Design

EXPERIENCE

Mehta Research Group/GazzolaLab, UIUC

Undergraduate Research Assistant - Soft Robotics

- Connected fiber-reinforced soft actuators in parallel and implemented joystick control for the robotic soft arm using a Raspberry • Pi to control pneumatic solenoid valves. Implemented a recursive low-pass-filter to enhance joystick input in real-time.
- Designed and built a 3D calibration grid using laser-cut acrylic and green paint; developed Python code utilizing OpenCV and • scikit-image to detect colored blobs and extract marker coordinates.
- Developed scripts to input arm pose maneuver instructions to allow rigorous comparison between simulation and real-world.
- Working on implementing multiple joystick-controlled arms for interacting with real-world objects and accurate joystick control of simulated arm using the Cosserat Rod model.

Skydio

Product Design Engineering Intern

- Design for Injection Molding: Utilized CATIA 3DEXPERIENCE to redesign the Navigation Camera mounting mechanism for the company's next generation performance quadcopter drone.
- Communicated with overseas vendors in China to implement design change, ensuring injection moldability and minimal lead • time. Kicked off injection mold retooling for newly redesigned Navigation Cameras.
- Designed and prototyped the mobile tablet adapter for the next generation drone controller using FDM and SLS 3D-Printing. • Received DFM feedback from injection molding vendor.
- Worked with Manufacturing Engineers to design wire routing layout for drone RF cables, board to board connections, 3-phase • motor power cables, LED cables.
- Designed custom wire clips and wire guides for injection molding, prioritizing ease of assembly while also taking into consideration potential interference from RF-sensitive electronics.

Lucid Motors

Mechanical Engineering Intern, High Voltage

- Battery Pack Development: Improved design for the high voltage chain halving the number of bolts required to join busbars. Conducted thermal analysis on busbar joints with new design to evaluate the new design's effect on car's horsepower, range, efficiency, and thermal endurance.
- Devised a method of measuring resistance of busbar joints up to 50% more accurate than the HIOKI low ohmmeter. •
- Collected and analyzed data on heat generation from bolted busbars joints, and used this data to calculate theoretical horsepower and efficiency loss of specific joints.

PROJECTS

Senior Capstone Project - Neurosurgical Balloon Tunnelling Device

- Developed an innovative shunt passage method using expandable balloons for ventriculoperitoneal operations which minimizes tissue damage and backtracking leading to improved patient and surgeon comfort.
- Built a pump controller to test both pneumatic and hydraulic balloons, integrating an Arduino microcontroller, I2C pressure sensors, and motor control circuitry (H-bridge, flyback diodes, solenoid exhaust valves)

GPA: 3.95/4.00 May 2024

JAN 2023 - PRESENT

MAY 2022 - AUGUST 2022

MAY 2021 - AUGUST 2021